

# Semidefinite programming

## Interior-point methods: the central path

Imre Pólik, PhD

Lehigh University  
Department of Industrial and Systems Engineering

January 29, 2009

# Outline

## Outline

### The central path

- 1 The central path
  - Orthogonality property
  - Perturbed complementarity conditions
  - Barrier functions
  - Primal and dual barrier problems
  - Properties of the central path

# Orthogonality of feasible steps

## Outline

### The central path

Orthogonality  
property

Perturbed  
complementarity  
conditions

Barrier functions

Primal and dual  
barrier problems

Properties of the  
central path

$$\min C \bullet X$$

$$\mathcal{A}X = b$$

$$X \succeq 0$$

$$\max b^T y$$

$$\mathcal{A}^* y + S = C$$

$$S \succeq 0$$

## Lemma

*If  $X_1, X_2$  are primal feasible and  $S_1, S_2$  are dual feasible, then  $(X_1 - X_2) \bullet (S_1 - S_2) = 0$ . In other words, the primal and dual feasible directions  $\Delta X$  and  $\Delta S$  are orthogonal.*

## Outline

## The central path

Orthogonality  
propertyPerturbed  
complementarity  
conditions

Barrier functions

Primal and dual  
barrier problemsProperties of the  
central path

# The central path

- Optimality conditions

$$\begin{array}{rcl}
 & \mathcal{A}X & = b \\
 \mathcal{A}^*y & & + S = C \\
 & XS & = 0 \\
 & X, S & \succeq 0,
 \end{array}$$

- Perturbation:

$$\begin{array}{rcl}
 & \mathcal{A}X & = b \\
 \mathcal{A}^*y & & + S = C \\
 & XS & = \mu I \\
 & X, S & \succeq 0,
 \end{array}$$

- Existence?
- Uniqueness?
- Analiticity?
- Convergence?

# Optimality conditions for the barrier problem

Consider

$$\begin{aligned} \min f(x) \\ Ax = b \\ x \geq 0, \end{aligned} \tag{NLP}$$

where  $f(x)$  is a convex function.

Rewrite it as

$$\begin{aligned} \min f(x) - \mu \sum_i \log x_i \\ Ax = b, \end{aligned} \tag{NLP}_\mu$$

where  $\mu > 0$ . Properties:

- The objective function is strictly convex if  $\mu > 0$ .
- As  $\mu \rightarrow 0$  the optimal solutions of  $(\text{NLP}_\mu)$  converge to an optimal solution of (NLP).

# Barrier functions for semidefinite optimization

Consider

$$\phi(X) = -\ln \det(X)$$

Properties:

- $\phi(X) = -\sum_{i=1}^n \ln \lambda_i(X)$
- $\phi(X) < \infty \Leftrightarrow X \succ 0$
- $\phi(X) \rightarrow \infty$  if  $X$  is approaching the boundary of  $\mathbb{S}_+^{n \times n}$
- $\phi(X)$  is differentiable

$$\phi'(X) = -X^{-1}$$

$$\phi''(X)[U, V] = (X^{-1}UX^{-1}) \bullet V$$

$$\phi'''(X)[U, V, W] = \dots$$

- $\phi(X)$  is strictly convex

Outline

The central path

Orthogonality  
property

Perturbed  
complementarity  
conditions

Barrier functions

Primal and dual  
barrier problems

Properties of the  
central path

## Outline

## The central path

Orthogonality  
propertyPerturbed  
complementarity  
conditions

Barrier functions

Primal and dual  
barrier problemsProperties of the  
central path

## SDP with a barrier

Primal barrier problem:

$$\begin{aligned} \min C \bullet X - \mu \ln \det(X) \\ \mathcal{A}X = b \end{aligned}$$

Dual barrier problem:

$$\max b^T y + \mu \ln \det(C - \mathcal{A}^* y)$$

Optimality conditions:

$$\begin{aligned} \mathcal{A}X &= b \\ \mathcal{A}^* y + S &= C \\ XS &= \mu I \\ X, S &\succ 0, \end{aligned}$$

## Outline

## The central path

Orthogonality  
property  
Perturbed  
complementarity  
conditions  
Barrier functions  
Primal and dual  
barrier problems  
Properties of the  
central path

# Properties of the central path

If both the primal and dual problems are strictly feasible, then

- The central path exists.
- The central path is unique.
- The central path is an analytic curve.
- As  $\mu \rightarrow 0$ , the central path converges to a maximally complementary optimal solution.
- If strict complementarity holds, then the central path converges to the analytic center of the optimal set.

The idea behind interior-point methods is to follow the central path.